If  $\frac{dy}{dx} = f(x, y)$  can be expressed as a function of  $\frac{y}{x}$  then *homogeneous*; make the substitution:  $\nu = \frac{y}{x}$   $\frac{dy}{dx} + P(x)y = Q(x)y^{\alpha} \quad \alpha \neq 0, 1$ is a *Bernoulli equation* make the substitution:  $u = y^{1-\alpha}$ 

A first order differential equation is called **linear** if it is expressible in the form:  $\frac{dy}{dx} + P(x)y = Q(x)$ , then  $\mu = e^{\int P(x)dx}$ .

$$M(x, y)dx + N(x, y)dy = 0 \quad \text{is exact iff} \quad \frac{\partial M}{\partial y}(x, y) = \frac{\partial N}{\partial x}(x, y)$$
  
Use  $\frac{\partial F}{\partial x} = M(x, y)dx \quad \text{or} \quad \frac{\partial F}{\partial y} = N(x, y)$ 

HOMOGENEOUS Techniques for Second Order Equations

- Constant Coefficients: Characteristic equation has roots r<sub>1</sub>, r<sub>2</sub>.
  - 1. Two distinct, real r's: general soln is  $y(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}$
  - 2. One repeated real r : general soln is  $y(t) = c_1 e^{rt} + c_2 t e^{rt}$
  - 3. Complex  $r = \alpha \pm \beta i$ : general soln is  $y(t) = c_1 e^{\alpha t} \cos \beta t + c_2 e^{\alpha t} \sin \beta t$
- Cauchy-Euler Equations: Have the form:

$$at^2y''(t) + bty'(t) + cy(t) = 0$$

with associated characteristic equation  $ar^2 + (b - a)r + c = 0$ .

- 1. Two distinct, real r's: general soln is  $y(t) = c_1 t^{r_1} + c_2 t^{r_2}$
- 2. One real *r*: general soln is  $y(t) = t^r(c_1 + c_2 \ln t)$
- 3. Complex  $r = \alpha \pm \beta i$ : general soln is  $y(t) = t^{\alpha} [c_1 \cos(\beta \ln t) + c_2 \sin(\beta \ln t)]$
- Reduction of Order

Equations of the form: y''(t) + p(t)y'(t) + q(t)y(t) = 0. If one solution  $y_1(t)$  to the DE is known; then let  $y_2(t) = u(t)y_1(t)$ .

## NON-HOMOGENEOUS Techniques for Second Order Equations

- Undetermined Coefficients Use ONLY when homogeneous part has constant coefficients and g(t) is constant, polynomial, sine, cosine, exponential, or the sum or product of these
- Variation of Parameters:

$$y''(t) + p(t)y'(t) + q(t)y(t) = f(t)$$

Look for a particular solution of the form:  $y_p(t) = v_1(t)y_1(t) + v_2(t)y_2(t)$ , where  $v_1$  and  $v_2$  satisfy the following conditions:

- 1.  $v_1'y_1 + v_2'y_2 = 0$
- 2.  $v_1'y_1' + v_2'y_2' = f$

• Linear Homogeneous Systems with Constant Coefficients

For 2x2 systems of the form  ${\bm x}\,'={\bm A}{\bm x}$  where all the entries of  ${\bm A}$  are constants,

1. If A has two, real, distinct eigenvalues,  $\lambda_1 \neq \lambda_2$ , with corresponding eigenvectors,  $\mathbf{v}_1$  and  $\mathbf{v}_2$  respectively then,

$$\mathbf{x}(t) = c_1 \mathbf{v}_1 e^{\lambda_1 t} + c_2 \mathbf{v}_2 e^{\lambda_2 t}$$

2. If A has complex eigenvalues,  $\lambda = \alpha \pm \beta i$ , with corresponding eigenvectors,  $\mathbf{v} = \mathbf{a} \pm \mathbf{b} i$  then,

$$\mathbf{x}(t) = c_1 e^{\alpha t} (\mathbf{a} \cos\beta t - \mathbf{b} \sin\beta t) + c_2 e^{\alpha t} (\mathbf{a} \sin\beta t + \mathbf{b} \cos\beta t)$$

• Integration

$$\int \frac{1}{a^2 + u^2} du = \frac{1}{a} \tan^{-1} \frac{u}{a} + C$$

$$\int \frac{2x - 1}{x^2} e^{2x} dx = \frac{e^{2x}}{x} + C$$

$$\int \sec t \, dt = \ln|\sec t + \tan t| + C$$

$$\int \csc t \, dt = \ln\left|\tan\left(\frac{t}{2}\right)\right| + C$$

• Trig Identities

$$\cos^2 \theta = \frac{1 + \cos(2\theta)}{2}$$
  $\sin^2 \theta = \frac{1 - \cos(2\theta)}{2}$   $\sin(2\theta) = 2\sin\theta\cos\theta$